JERRI randomly travels where he pleases, with a beam of light shining out behind him. TOM uses his five sensors to track and chase Jerri.

The Final System (in Disguise)
Interactive C programs are written on a PC and then downloaded to the robot using a *Serial Interface Board*. It connects to the serial port of the computer to the Handy Board, which is the brains of the robot. It is capable of accepting both digital and analog input signals.

Tom and Jerri are fully autonomous robots like Tom & Jerri are programmed to have intelligence. We wrote ours in Interactive C (IC) which is a subset of the C language.

Tom and Jerri are able to make decisions based on input read from sensors. These sensors are plugged into the Handy Board.